

On the Classification of Nilpotent Lie Algebras

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Abstract. We establish a bijective correspondence between all central extensions of fixed Lie algebra \mathcal{G} by \mathbb{R}^k (with k -dimensional centers), and certain orbits in the set of all k -dimensional subspaces in the second cohomology group $H^2(\mathcal{G}, \mathbb{R})$, under the canonical action of $\text{Aut}(\mathcal{G})$. As an application we construct all six-dimensional nilpotent Lie algebras over \mathbb{R} (finitely many). We also show that there are infinitely many mutually non-isomorphic two-step real Lie algebras of dimension nine.

1. Introduction. In this article we develop a method of constructing all nilpotent Lie algebras of dimension n given those algebras of dimension $< n$, and their automorphism groups. Roughly speaking, we establish a bijective correspondence between all central extensions of a fixed Lie algebra \mathcal{G} by \mathbb{R}^k with k -dimensional centers, and certain orbits in the set of all k -dimensional subspaces in the second cohomology group $H^2(\mathcal{G}, \mathbb{R})$, under the canonical action of $\text{Aut}(\mathcal{G})$. For natural reasons we are working in the space S of all bilinear forms on \mathcal{G} with values in \mathbb{R}^k satisfying the Jacobi identity, rather than in $H^2(\mathcal{G}, \mathbb{R}^k)$. If $B \in S$, the action of $\text{Aut}(\mathcal{G})$ on B is simply given by

$$(\alpha, B) \mapsto B^\alpha, \text{ where } B^\alpha(X, Y) = B(\alpha X, \alpha Y); X, Y \in \mathcal{G}, \alpha \in \text{Aut}(\mathcal{G}).$$

As an application of our procedure, we find all nilpotent Lie algebras over \mathbb{R} of dimension 6 (finitely many). Recall that Dixmier has classified all such algebras of dimension ≤ 5 , [1]. We will also show that there are infinitely many mutually non-isomorphic real two-step Lie algebras of dimension 9 with center of dimension 3. Even if our method is straight forward, the computations of $\text{Aut}(\mathcal{G})$ -orbits in $H^2(\mathcal{G}, \mathbb{R}^k)$ are in general far from easy to carry out, and at the moment a complete classification of nilpotent Lie algebras seems to be out of reach.

2. Central extensions and automorphisms.

2.1. Let \mathcal{G} be a Lie algebra over \mathbb{R} , $B : \mathcal{G} \times \mathcal{G} \rightarrow \mathbb{R}^k$ a skew symmetric bilinear form satisfying the Jacobi identity

$$(2.1) \quad B([X, Y], Z) + B([Z, X], Y) + B([Y, Z], X) = 0, \quad \text{all } X, Y, Z \in \mathcal{G}.$$

Such forms are said to be closed. If B is a closed form on \mathcal{G} we construct a Lie algebra on $\mathcal{G} \oplus \mathbb{R}^k$, letting $\left[\begin{pmatrix} X \\ u \end{pmatrix}, \begin{pmatrix} Y \\ v \end{pmatrix} \right] = \begin{pmatrix} [X, Y] \\ B(X, Y) \end{pmatrix}$; $X, Y \in \mathcal{G}$, $u, v \in \mathbb{R}^k$. Denote this Lie algebra by $\mathcal{G}(B)$.

Let now $\tilde{\mathcal{G}}$ be a Lie algebra with center $\tilde{\mathcal{Z}}$ and $\dim \tilde{\mathcal{Z}} = k$, $\gamma : \tilde{\mathcal{G}} \rightarrow \mathbb{R}^k$ be linear and such that $\gamma(\tilde{\mathcal{Z}}) = \mathbb{R}^k$. We put $\mathcal{G} = \tilde{\mathcal{G}}/\tilde{\mathcal{Z}}$ and get an isomorphism $\tilde{\mathcal{G}} \cong \mathcal{G} \oplus \mathbb{R}^k$ where $\tilde{X} \leftrightarrow \begin{pmatrix} Y \\ u \end{pmatrix}$, $\gamma(\tilde{X}) = u$, and $Y = \tilde{X} + \tilde{\mathcal{Z}} \in \tilde{\mathcal{G}}/\tilde{\mathcal{Z}} = \mathcal{G}$. We put $B = \gamma \circ [\cdot, \cdot]$, that is

$$B(X, Y) = \gamma[X', Y']; \quad \text{where } X' + \tilde{\mathcal{Z}} = X, \quad Y' + \tilde{\mathcal{Z}} = Y.$$

This shows $\tilde{\mathcal{G}}$ and $\mathcal{G}(B)$ are isomorphic. Hence each Lie algebra with center of dimension k is of the form $\mathcal{G}(B)$ where $B : \mathcal{G} \times \mathcal{G} \rightarrow \mathbb{R}^k$.

2.2. Let $B: \mathcal{G} \times \mathcal{G} \rightarrow \mathbb{R}^k$ be a closed form. Then the center $\tilde{\mathcal{Z}}$ of $\tilde{\mathcal{G}} = \mathcal{G}(B)$ is equal to

$$\tilde{\mathcal{Z}} = \mathbb{R}^k \oplus (\mathcal{Z} \cap \mathcal{S}_B), \text{ where } \mathcal{S}_B = \{X \in \mathcal{G} : B(X, \mathcal{G}) = (0)\}$$

2.3. Given two such forms $B_1, B_2: \mathcal{G} \times \mathcal{G} \rightarrow \mathbb{R}^k$, and assume the extended algebras $\mathcal{G}(B_1)$ and $\mathcal{G}(B_2)$ are isomorphic and that their centers $\tilde{\mathcal{Z}}_1$ and $\tilde{\mathcal{Z}}_2$ both are equal to \mathbb{R}^k . Let $\alpha: \mathcal{G}(B_1) \rightarrow \mathcal{G}(B_2)$ be an isomorphism. Dividing with the common center \mathbb{R}^k we obtain an automorphism $\alpha_0: \mathcal{G} \rightarrow \mathcal{G}$. Let us fix a basis $\{e_1, \dots, e_n\}$ for \mathcal{G} , and supplement it with a basis for \mathbb{R}^k to get a basis \mathcal{E} for $\mathcal{G} \oplus \mathbb{R}^k$. We may realize α as a matrix relative to \mathcal{E} :

$$(2.2) \quad \alpha = \left(\begin{array}{c|c} \alpha_0 & 0 \\ \hline \varphi & \psi \end{array} \right); \alpha_0 \in \text{Aut}(\mathcal{G}), \psi = \alpha|_{\tilde{\mathcal{Z}}} \in \text{GL}(k), \text{ and } \varphi \in \text{Hom}(\mathcal{G}, \mathbb{R}^k).$$

Now α preserves the brackets, and writing $[\cdot, \cdot]_i$ for the products in $\mathcal{G}(B_i)$, $i = 1, 2$, and $[\cdot, \cdot]$ for the product in \mathcal{G} , we have

$$\alpha \left[\begin{pmatrix} X \\ 0 \end{pmatrix}, \begin{pmatrix} Y \\ 0 \end{pmatrix} \right]_1 = \left[\alpha \begin{pmatrix} X \\ 0 \end{pmatrix}, \alpha \begin{pmatrix} Y \\ 0 \end{pmatrix} \right]_2, \quad X, Y \in \mathcal{G},$$

where $\alpha \begin{pmatrix} X \\ 0 \end{pmatrix} = \begin{pmatrix} \alpha_0 X \\ \varphi X \end{pmatrix}$, and hence

$$\left[\alpha \begin{pmatrix} X \\ 0 \end{pmatrix}, \alpha \begin{pmatrix} Y \\ 0 \end{pmatrix} \right]_2 = \left[\begin{pmatrix} \alpha_0 X \\ \varphi X \end{pmatrix}, \begin{pmatrix} \alpha_0 Y \\ \varphi Y \end{pmatrix} \right]_2 = \begin{pmatrix} [\alpha_0 X, \alpha_0 Y] \\ B_2(\alpha_0 X, \alpha_0 Y) \end{pmatrix}$$

and

$$\alpha \left[\begin{pmatrix} X \\ 0 \end{pmatrix}, \begin{pmatrix} Y \\ 0 \end{pmatrix} \right]_1 = \alpha \begin{pmatrix} [X, Y] \\ B_1(X, Y) \end{pmatrix} = \begin{pmatrix} \alpha_0 [X, Y] \\ \varphi [X, Y] + \psi B_1(X, Y) \end{pmatrix}.$$

Hence

$$(2.3) \quad B_2(\alpha_0 X, \alpha_0 Y) = \varphi [X, Y] + \psi B_1(X, Y), \quad \text{all } X, Y \in \mathcal{G}.$$

In case $B_1 = B_2 = B$, we get the following description of the automorphism group $\text{Aut}(\mathcal{G}(B))$.

2.4. Proposition. Let B be a closed form on the Lie algebra \mathcal{G} with values in \mathbb{R}^k , and assume $\mathcal{J}_B \cap \mathcal{Z}(\mathcal{G}) = (0)$. Then the automorphism group $\text{Aut } \mathcal{G}(B)$ of the extended algebra $\mathcal{G}(B)$ consists of all linear operators of the matrix form $\alpha = \left(\begin{array}{c|c} \alpha_0 & 0 \\ \hline \varphi & \psi \end{array} \right)$ as in (2.2), where

$$(2.4) \quad B(\alpha_0 X, \alpha_0 Y) = \psi B(X, Y) + \varphi[X, Y], \quad \text{all } X, Y \in \mathcal{G}.$$

2.5. Examples. The Heisenberg algebra \mathcal{G}_3 with non-zero brackets $[e_1, e_2] = e_3$ between the basis elements e_1, e_2, e_3 is a central extension of the abelian algebra $\mathcal{G} = \mathbb{R}e_1 \times \mathbb{R}e_2$ by $\mathbb{R}e_3$, given by the bilinear form $B = B_{12} : (\sum x_i e_i, \sum y_i e_i) \rightarrow x_1 y_2 - x_2 y_1$. Now $\mathcal{J}_B = (0)$ and $\text{Aut}(\mathcal{G}_3)$ consists of all operators

$$(2.5) \quad \begin{pmatrix} a & b & 0 \\ c & d & 0 \\ u_1 & u_2 & c_0 \end{pmatrix}, \quad \text{where } ad - bc = c_0 \neq 0.$$

The four dimensional nilpotent Lie algebra \mathcal{G}_4 given by $[e_1, e_2] = e_3$, $[e_1, e_3] = e_4$ is a central extension of \mathcal{G}_3 by $\mathbb{R}e_4$, given by the bilinear form $B = B_{13} : (\sum_{i=1}^3 x_i e_i, \sum_{i=1}^3 y_i e_i) \rightarrow x_1 y_3 - x_3 y_1$. Thus $\mathcal{J}_B \cap \mathcal{Z}(\mathcal{G}_3) = (0)$, and $\text{Aut } \mathcal{G}_4$ consists of all operators $\alpha = \left(\begin{array}{c|c} \alpha_0 & 0 \\ \hline \varphi & c_1 \end{array} \right)$, $\alpha_0 \in \text{Aut } \mathcal{G}_3$, $\varphi \in \mathcal{G}_3^*$, $c_1 \in \mathbb{R}$, such that (2.4) is satisfied. This gives

$$(2.6) \quad \alpha = \begin{pmatrix} a & 0 & 0 & 0 \\ c & d & 0 & 0 \\ u_1 & u_2 & ad & 0 \\ v_1 & v_2 & au_2 & a^2 d \end{pmatrix}, \quad ad \neq 0.$$

On the basis of $\text{Aut } \mathcal{G}_3$ and $\text{Aut } \mathcal{G}_4$ one computes without difficulty the automorphism groups of all five-dimensional nilpotent Lie algebras. These can be found in Table 4.3. (except for $\text{Aut}(\mathcal{G}_{5,1})$ which is not needed).

3. Central extensions of Lie algebras.

3.1. We continue our study of central extensions $\mathcal{G}(B)$ of a Lie algebra \mathcal{G} given by closed forms $B: \mathcal{G} \times \mathcal{G} \rightarrow \mathbb{R}^k$, and proceed to exclude forms B such that $\mathcal{G}(B) \cong \mathbb{R} \times \mathcal{G}(B')$, where $B': \mathcal{G} \times \mathcal{G} \rightarrow \mathbb{R}^{k-1}$. Let J be the set of all linear maps $F: \mathbb{R}^k \rightarrow \mathbb{R}^k$ such that there exists a linear map $\varphi: \mathcal{G} \rightarrow \mathbb{R}^k$ with the property

$$(3.1) \quad F(B(X,Y)) = \varphi[X,Y], \quad \text{all } X,Y \in \mathcal{G}.$$

Clearly J is a left ideal of $\text{Hom}(\mathbb{R}^k, \mathbb{R}^k)$, i.e. $J = \text{Hom}(\mathbb{R}^k, \mathbb{R}^k) \circ J$, and therefore J is generated by a projection π ; $J = \text{Hom}(\mathbb{R}^k, \mathbb{R}^k) \circ \pi$. We have

$$\pi(B(X,Y)) = \varphi_\pi[X,Y], \quad \varphi_\pi \in \text{Hom}(\mathcal{G}, \mathbb{R}^k).$$

Put

$$(3.2) \quad B'(X,Y) = B(X,Y) - \varphi_\pi[X,Y] = (1-\pi)B(X,Y),$$

in particular B' is cohomologous to B .

3.2. Lemma. Suppose we have an equation

$$F(B'(X,Y)) = \varphi[X,Y], \quad \text{all } X,Y \in \mathcal{G},$$

where $\varphi \in \text{Hom}(\mathcal{G}, \mathbb{R}^k)$ and B' is given by (3.2).

Then $\varphi[X,Y] = 0$, all $X,Y \in \mathcal{G}$.

Proof. If the above equality holds, then

$$F \circ (1-\pi)B(X,Y) = \varphi[X,Y], \quad \text{all } X,Y \in \mathcal{G},$$

so that $F \circ (1-\pi) \in J$, and hence $F \circ (1-\pi) = G \circ \pi$, $G \in \text{Hom}(\mathbb{R}^k, \mathbb{R}^k)$, and $F = (G+F) \circ \pi$; hence

$$F \circ (1-\pi) = (G+F) \circ \pi \circ (1-\pi) = (G+F) \circ (\pi - \pi) = 0.$$

3.3. It follows from (3.2) that $\mathcal{G}(B)$ and $\mathcal{G}(B') = \mathcal{G}(B - \varphi_\pi[\cdot, \cdot])$ are isomorphic. Suppose $\pi \neq 0$ ($J \neq (0)$), then obviously

$$\mathcal{G}(B') = \mathcal{G}(B'_0) \times \pi(\mathbb{R}^k)$$

where $\pi(\mathbb{R}^k)$ is abelian and

$$B'_0 = (1-\pi) \circ B : \mathcal{G} \times \mathcal{G} \rightarrow (1-\pi)\mathbb{R}^k.$$

Corollary. Let $\mathcal{J}_B \cap \mathcal{J} = (0)$ and assume that $\mathcal{G}(B)$ can not be written as $\mathbb{R} \times \mathcal{G}$ for any Lie algebra \mathcal{G} . For any pair of linear maps $F : \mathbb{R}^k \rightarrow \mathbb{R}^k$, $\varphi : \mathcal{G} \rightarrow \mathbb{R}^k$ such that $F \circ B(X, Y) = \varphi[X, Y]$, we have $F = 0$.

We can always assume the corollary holds, since we are not interested in algebras of the form $\mathbb{R} \times \mathcal{G}$.

3.4. In order to classify Lie algebras $\tilde{\mathcal{G}}$ with no factor isomorphic to \mathbb{R} , and with center $\tilde{\mathcal{J}}$ of dimension k and $\tilde{\mathcal{G}}/\tilde{\mathcal{J}} \cong \mathcal{G}$, we must consider closed forms $B : \mathcal{G} \times \mathcal{G} \rightarrow \mathbb{R}^k$ as in Corollary 3.3. Let S be the vector space of all closed forms on \mathcal{G} , and let S' be the subspace of all exact forms $B(X, Y) = \varphi[X, Y]$ where $\varphi : \mathcal{G} \rightarrow \mathbb{R}^k$ is linear, i.e. $\varphi \in \mathcal{G}^*$. Then Corollary 3.3 is equivalent to the following: Let $\pi_1, \dots, \pi_k : \mathbb{R}^k \rightarrow \mathbb{R}$ be the coordinate functionals, then $\pi_1 \circ B, \dots, \pi_k \circ B$ are linearly independent in S/S' . We know from § 2.3 that $\mathcal{G}(B_1) \cong \mathcal{G}(B_2) \iff B_2(\alpha_0 X, \alpha_0 Y) = \psi B_1(X, Y) + \varphi[X, Y]$ where $\alpha = \begin{pmatrix} \alpha_0 & 0 \\ \varphi & \psi \end{pmatrix}$ is an isomorphism. Such an identity holds if and only if $\pi_1 \circ B_1, \dots, \pi_k \circ B_1$ and $\pi_1 \circ B_2 \circ \alpha_0, \dots, \pi_k \circ B_2 \circ \alpha_0$ generate the same subspace of S/S' . We say that an $\text{Aut}(\mathcal{G})$ -orbit Ω in the set of all k -dimensional subspaces of S/S' has no kernel in the center \mathcal{J} of \mathcal{G} if $\mathcal{J}_B \cap \mathcal{J} = (0)$ for some (and hence for all)

$B \in \Omega$. Up to this point we have made no use of the fact that \mathcal{G} was a real Lie algebra, thus we may state the following result for Lie algebras over arbitrary fields.

3.5. Theorem. Let \mathcal{G} be a Lie algebra over a field K . The isomorphism classes of Lie algebras $\tilde{\mathcal{G}}$ with center $\tilde{\mathcal{Z}}$ of dimension k , $\mathcal{G}/\tilde{\mathcal{Z}} \cong \mathcal{G}$, and without abelian direct factors, are in bijective correspondence with those $\text{Aut}(\mathcal{G})$ -orbits in the set of all k -dimensional subspaces of S/S' which have no kernel in \mathcal{Z} .

Let $\Lambda_2 \mathbb{R}^k$ be the set of all skew symmetric bilinear forms on \mathbb{R}^k with values in \mathbb{R} , and let $G_n(V)$ = the set of all n -dimensional subspaces of a vector space V . As an application to the above theorem we get

3.6. Proposition. There are infinitely many mutually non-isomorphic nilpotent real Lie algebras of dimension 9.

Proof. We will consider only those algebras \mathcal{G} with $\dim \mathcal{Z} = 3$ and with $\mathcal{G}/\mathcal{Z} \cong \mathbb{R}^6$. By Theorem 3.5 the isomorphism classes of such algebras are in bijective correspondence with certain orbits of $GL(6)$ in $G_3(\Lambda_2 \mathbb{R}^6)$. Letting U be the Zariski-open subset of $G_3(\Lambda_2 \mathbb{R}^6)$ of those 3-dimensional subspaces Q with $\mathcal{J}_Q = (0)$, the orbits of $GL(6)$ in U are in bijective correspondence with the isomorphism classes of Lie algebras which we consider. We have

$$\dim U = \dim G_3(\Lambda_2 \mathbb{R}^6) = 3 \cdot ((\binom{6}{2}) - 3) = 36$$

and $\dim GL(6) = 36$. However, since the center of $GL(6)$ is acting trivially, the orbits are of dimension ≤ 35 . Since U is not a union of a finite number of analytic submanifolds of dimension less than $\dim U$, the proof is complete.

4. Six-dimensional nilpotent Lie algebras with center of dimension one.

4.1. By virtue of Theorem 3.5 we can, at least in principle, classify all nilpotent Lie algebras of dimension n , given all such algebras of dimension $< n$, and their automorphism groups. As an application we shall work out this program for $n = 6$, and we start with the class of algebras having one-dimensional center. According to [1] the algebras of dimension 5 which we have to extend are the following

$$\mathcal{G}_3 \times \mathbb{R}^2, \mathcal{G}_4 \times \mathbb{R}, \mathcal{G}_{5,1}, \mathcal{G}_{5,2}, \mathcal{G}_{5,3}, \mathcal{G}_{5,4}, \mathcal{G}_{5,5}, \mathcal{G}_{5,6}.$$

We shall illustrate the computations by means of two examples. The remaining six algebras are treated analogously, and the result, **thirteen** new algebras, is listed in the table 4.3.

If $\{e_1, \dots, e_n\}$ is a fixed basis for the Lie algebra \mathcal{G} , we let $B_{ij} : (\sum_{i=1}^n x_i e_i, \sum_{i=1}^n y_i e_i) \mapsto x_i y_j - x_j y_i, 1 \leq i < j \leq n$, denote the elementary bilinear forms.

4.2. Extensions of $\mathcal{G}_{5,4}$. $\mathcal{G}_{5,4}$ is given by the following non-zero bracket-relations between the elements of a basis:

$$[e_1, e_2] = e_3, [e_1, e_3] = e_4, [e_2, e_3] = e_5.$$

We first compute $\text{Aut}(\mathcal{G}_{5,4})$. Now $\mathcal{G}_{5,4}$ is a central extension of the Heisenberg algebra \mathcal{G}_3 by $\mathbb{R}e_4 \times \mathbb{R}e_5$ determined by the bilinear form $B = (B_{13}, B_{23})$, and hence $\mathcal{J}_B \cap \mathcal{J}(\mathcal{G}_3) = (0)$. By (2.2) and (2.5) every $\alpha \in \text{Aut} \mathcal{G}_{5,4}$ can be written

$$\alpha = \left(\begin{array}{c|cc} \alpha_0 & & 0 \\ \hline \varphi & b_0 & \beta_0 \\ & c_0 & \gamma_0 \end{array} \right); \quad \alpha_0 = \begin{pmatrix} a & b & 0 \\ c & d & 0 \\ u_1 & u_2 & e \end{pmatrix} \in \text{Aut}(\mathcal{G}_3), e = ad - bc \neq 0, \\ \varphi \in \text{Hom}(\mathcal{G}_3, \mathbb{R}^2).$$

Computing $\alpha[X, Y]$ and $[\alpha X, \alpha Y]$ (or using (2.4)) we find that

$$\alpha = \begin{pmatrix} a & b & 0 & 0 & 0 \\ c & d & 0 & 0 & 0 \\ u_1 & u_2 & e & 0 & 0 \\ b_1 & b_2 & au_2 - bu_1 & ae & be \\ c_1 & c_2 & cu_2 - du_1 & ce & de \end{pmatrix}, \quad ad - bc = e \neq 0.$$

Next we find a basis for the set S of all closed bilinear forms on $\mathcal{G}_{5,4}$, and we can compute modulo the exact forms S' . Thus

B_{12}, B_{13}, B_{23} is a basis for the space S' checking the Jacobi-identity (2.1) on all the remaining 7 elementary forms B_{ij} we find the following basis for S/S' : $B_{25}, B_{14}, B_{24} + B_{15}$.

Before computing orbits under $\text{Aut}(\mathcal{G}_{5,4})$ we recall that only the forms B with $\mathcal{J}_B \cap \mathcal{J}(\mathcal{G}_{5,4}) = (0)$ give new algebras with one-dimensional centers, in particular B_{25} and B_{14} do not satisfy this. For $\alpha \in \text{Aut}(\mathcal{G}_{5,4})$ we see (regarding the forms as matrices)

$$\alpha^t(B_{24} + B_{15})\alpha = 2eacB_{14} + 2ebd B_{25} + e(ad + bc)(B_{24} + B_{15}), \text{ (modulo } S'),$$

Hence $B_{14} + B_{25}$ is not in the orbit of $B_{24} + B_{15}$, however $B_{14} + B_{25}$ satisfies $\mathcal{J}_B \cap \mathcal{J}(\mathcal{G}_{5,4}) = (0)$. Now

$$\alpha^t(B_{14} + B_{25})\alpha = (a^2 + c^2)eB_{14} + (b^2 + d^2)eB_{25} + (ab + cd)e(B_{24} + B_{15}),$$

(modulo S'),

and

$$\alpha^t B_{25} \alpha = ec^2 B_{14} + ed^2 B_{25} + cde(B_{24} + B_{15}), \text{ (modulo } S').$$

In particular the orbits $\Omega(B_{25})$ and $\Omega(B_{14})$ are identical and this orbit forms a 2-dimensional surface separating the two open orbits $\Omega(B_{15} + B_{24})$ and $\Omega(B_{14} + B_{25})$. The two last orbits correspond to two different isomorphism classes of six-dimensional algebras, and these are the only classes arising from $\mathcal{G}_{5,4}$. Thus, within isomorphisms, the only extensions of $\mathcal{G}_{5,4}$ are given by the bracket relations of

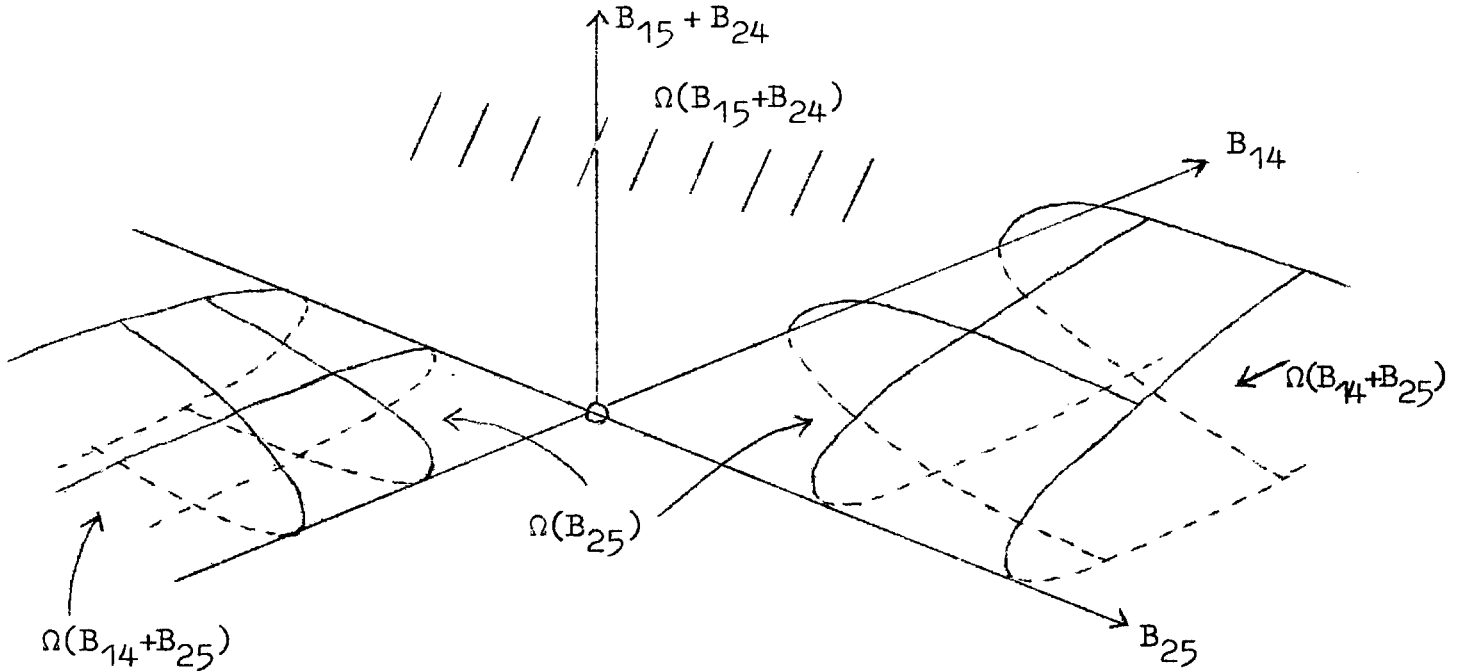
$\mathcal{G}_{5,4}$ together with the additional brackets,

$$[e_1, e_5] = [e_2, e_4] = e_6 \quad (\Omega(B_{15} + B_{24}))$$

and

$$[e_1, e_4] = [e_2, e_5] = e_6 \quad (\Omega(B_{14} + B_{25})).$$

We sketch the orbit space in S/S' :



(4.1) Orbits in $S/S' \cong H^2(\mathcal{G}_{5,4}, \mathbb{R})$ under $\text{Aut}(\mathcal{G}_{5,4})$.

4.2. Extensions of $\mathcal{G}_{5,6}$. $\mathcal{G}_{5,6}$ is given by the non-zero brackets

$$[e_1, e_2] = e_3, [e_1, e_3] = e_4, [e_1, e_4] = e_5, [e_2, e_3] = e_5.$$

Hence \mathcal{G}_{56} is a central extension of \mathcal{G}_4 by $\mathbb{R}e_5$, and every $\alpha \in \text{Aut}(\mathcal{G}_{5,6})$ is of the form (2.2) where $\alpha_0 \in \text{Aut}(\mathcal{G}_4)$ is determined by (2.6).

From the relation (2.4) we derive

$$\alpha = \begin{pmatrix} a & 0 & 0 & 0 & 0 \\ c & a^2 & 0 & 0 & 0 \\ u_1 & u_2 & a^3 & 0 & 0 \\ b_1 & b_2 & au_2 & a^4 & 0 \\ c_1 & c_2 & ab_2+cu_2-a^2u_1 & a^2u_2+ca^3 & a^5 \end{pmatrix}, a \neq 0.$$

A basis for S/S' is $\{B_{34}+B_{25}, B_{24}+B_{15}\}$, and a calculation of the action of $\text{Aut}(\mathcal{G}_{5,6})$ on each of these forms yields two orbits

$$\Omega = \{s(B_{15}+B_{24}) + t(B_{34}+B_{25}) : t \neq 0\}$$

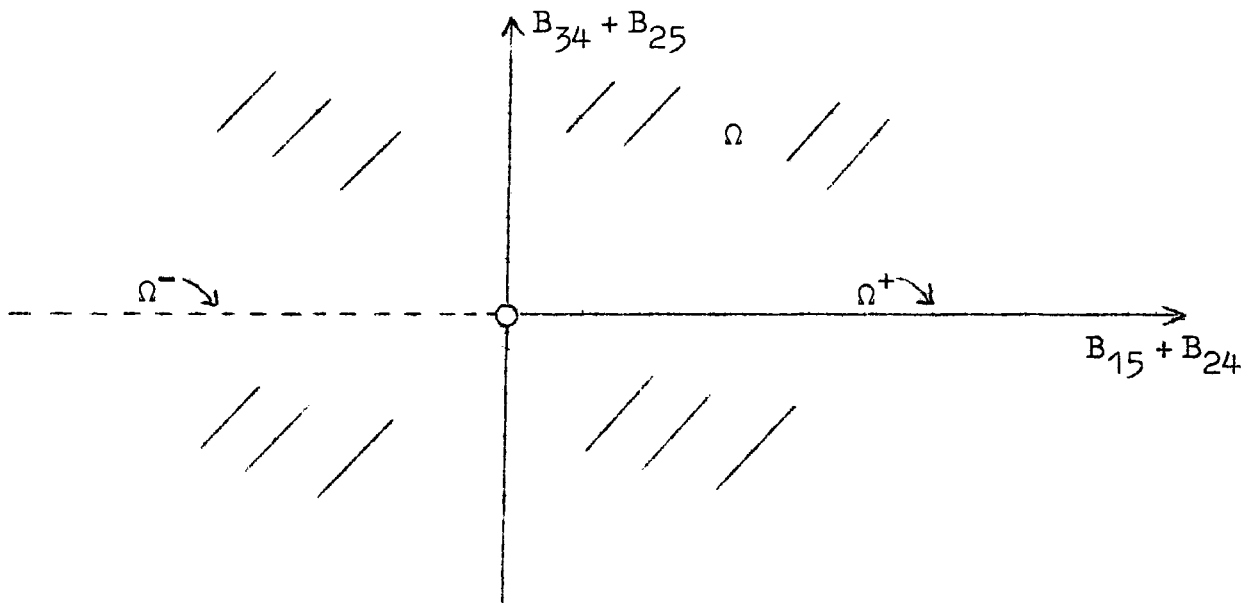
$$\Omega^+ = \{s(B_{15}+B_{24}) : s > 0\}.$$

In addition, we have the orbit $\Omega^- = \{s(B_{15}+B_{24}) : s < 0\}$. Of course, Ω^+ and Ω^- define the same isomorphism class of algebras. Thus, within isomorphisms, there are two extensions of $\mathcal{G}_{5,6}$ with one-dimensional center. They are given by the bracket relations of $\mathcal{G}_{5,6}$ and the additional relations:

$$[e_3, e_4] = [e_2, e_5] = e_6 \quad (\Omega)$$

and

$$[e_1, e_5] = [e_2, e_4] = e_6 \quad (\Omega^+)$$



(4.2) Orbits in $S/S' \cong H^2(\mathcal{G}_{5,6}, \mathbb{R})$ under $\text{Aut}(\mathcal{G}_{5,6})$.

4.3. Table. Six-dimensional real nilpotent Lie algebras $\tilde{\mathfrak{g}}$ with one-dimensional center $\tilde{\mathfrak{z}}$. $\tilde{\mathfrak{g}}/\tilde{\mathfrak{z}} = \mathfrak{g}$.

\mathfrak{g}	Basis for the set of closed non-exact forms on \mathfrak{g} ($H^2(\mathfrak{g})$)	$\text{Aut}(\mathfrak{g})$	Representative for defining orbit in $H^2(\mathfrak{g})$	Product in $\tilde{\mathfrak{g}}$. Only non-zero brackets are given.	$\tilde{\mathfrak{g}}$
$\mathfrak{g}_3 \times \mathbb{R}^2$	$B_{13}, B_{23}, B_{24},$ $B_{25}, B_{14}, B_{15},$ B_{45}	$\begin{pmatrix} a & b & 0 & 0 & 0 \\ c & d & 0 & 0 & 0 \\ b_1 & b_2 & c_0 & b_3 & b_4 \\ c_1 & c_2 & 0 & c_3 & c_4 \\ u_1 & u_2 & 0 & u_3 & u_4 \end{pmatrix}$ $c_0 = ad - bc \neq 0$ $c_3 u_4 - u_3 c_4 \neq 0$	$B_{13} + B_{45}$	$[e_1, e_2] = e_3$ $[e_1, e_3] =$ $[e_4, e_5] = e_6$	$\mathfrak{g}_{6,1}$
$\mathfrak{g}_4 \times \mathbb{R}$	$B_{15}, B_{25},$ B_{14}, B_{23}	$\begin{pmatrix} a & 0 & 0 & 0 & 0 \\ c & d & 0 & 0 & 0 \\ u_1 & u_2 & ad & 0 & 0 \\ b_1 & b_2 & au_2 & a^2 d & a_0 \\ v_1 & v_2 & 0 & 0 & c_0 \end{pmatrix}$ $\text{ad} c_0 \neq 0$	$B_{14} + B_{25}$	$[e_1, e_2] = e_3$ $[e_1, e_3] = e_4$ $[e_1, e_4] =$ $[e_2, e_5] = e_6$	$\mathfrak{g}_{6,2}$
			$B_{14} + B_{25} + B_{23}$	$[e_1, e_2] = e_3$ $[e_1, e_3] = e_4$ $[e_1, e_4] =$ $[e_2, e_5] =$ $[e_2, e_3] = e_6$	$\mathfrak{g}_{6,3}$
$\mathfrak{g}_{5,1}$	B_{13}, B_{14} B_{23}, B_{24}		-	-	-
$\mathfrak{g}_{5,2}$	$B_{14}, B_{15}, B_{24},$ $B_{35}, B_{25} + B_{34},$ B_{23}	$\begin{pmatrix} a & 0 & 0 & 0 & 0 \\ d & e & f & 0 & 0 \\ g & h & k & 0 & 0 \\ u_1 & u_2 & u_3 & ae & af \\ v_1 & v_2 & v_3 & ah & ak \end{pmatrix}$ $a \neq 0, ek \neq hf$	$B_{25} + B_{34}$	$[e_1, e_2] = e_4$ $[e_1, e_3] = e_5$ $[e_2, e_5] =$ $[e_3, e_4] = e_6$	$\mathfrak{g}_{6,4}$
			$B_{35} + B_{14}$	$[e_1, e_2] = e_4$ $[e_1, e_3] = e_5$ $[e_1, e_4] =$ $[e_3, e_5] = e_6$	$\mathfrak{g}_{6,5}$
			$B_{24} + B_{35}$	$[e_1, e_2] = e_4$ $[e_1, e_3] = e_5$ $[e_2, e_4] =$ $[e_3, e_5] = e_6$	$\mathfrak{g}_{6,6}$

$\mathcal{G}_{5,3}$	$B_{15}-B_{34}$ B_{24}, B_{13}	$\begin{pmatrix} a & 0 & 0 & 0 & 0 \\ 0 & d & 0 & 0 & 0 \\ u_1 & u_2 & a^2 & 0 & 0 \\ v_1 & v_2 & 0 & ad & 0 \\ b_1 & b_2 & b_3 & b_4 & a^2d \end{pmatrix}$ $b_4 = av_2 - du_1, ad \neq 0$	$B_{15} - B_{34}$	$[e_1, e_2] = e_4$ $[e_1, e_4] =$ $[e_2, e_3] = e_5$ $[e_1, e_5] =$ $-[e_3, e_4] = e_6$	$\mathcal{G}_{6,7}$
$\mathcal{G}_{5,4}$	$B_{14}, B_{25},$ $B_{15}+B_{24}$	$\begin{pmatrix} a & b & 0 & 0 & 0 \\ c & d & 0 & 0 & 0 \\ u_1 & u_2 & e & 0 & 0 \\ b_1 & b_2 & b_3 & ae & be \\ c_1 & c_2 & c_3 & ce & de \end{pmatrix}$ $e = ad - bc \neq 0$ $b_3 = au_2 - bu_1,$ $c_3 = cu_2 - du_1$	$B_{15} + B_{24}$	$[e_1, e_2] = e_3$ $[e_1, e_3] = e_4$ $[e_2, e_3] = e_5$ $[e_1, e_5] =$ $[e_2, e_4] = e_6$	$\mathcal{G}_{6,8}$
			$B_{25} + B_{14}$	$[e_1, e_2] = e_3$ $[e_1, e_3] = e_4$ $[e_2, e_3] = e_5$ $[e_2, e_5] =$ $[e_1, e_4] = e_6$	$\mathcal{G}_{6,9}$
$\mathcal{G}_{5,5}$	B_{15}, B_{23}	$\begin{pmatrix} a & 0 & 0 & 0 & 0 \\ c & d & 0 & 0 & 0 \\ u_1 & u_2 & ad & 0 & 0 \\ b_1 & b_2 & au_2 & a^2d & 0 \\ c_1 & c_2 & ab_2 & a^2u_2 & a^3d \end{pmatrix}$ $ad \neq 0$	B_{15}	$[e_1, e_2] = e_3$ $[e_1, e_3] = e_4$ $[e_1, e_4] = e_5$ $[e_1, e_5] = e_6$	$\mathcal{G}_{6,10}$
			$B_{15} + B_{23}$	$[e_1, e_2] = e_3$ $[e_1, e_3] = e_4$ $[e_1, e_4] = e_5$ $[e_1, e_5] =$ $[e_2, e_3] = e_6$	$\mathcal{G}_{6,11}$
$\mathcal{G}_{5,6}$	$B_{24} + B_{15}$ $B_{25} + B_{34}$	$\begin{pmatrix} a & 0 & 0 & 0 & 0 \\ c & a^2 & 0 & 0 & 0 \\ u_1 & u_2 & a^3 & 0 & 0 \\ b_1 & b_2 & au_2 & a^4 & 0 \\ c_1 & c_2 & c_3 & c_4 & a^5 \end{pmatrix}$	$B_{24} + B_{15}$	$[e_1, e_2] = e_3$ $[e_1, e_3] = e_4$ $[e_1, e_4] =$ $[e_2, e_3] = e_5$ $[e_2, e_4] =$ $[e_1, e_5] = e_6$	$\mathcal{G}_{6,12}$
			$B_{34} + B_{25}$	$[e_1, e_2] = e_3$ $[e_1, e_3] = e_4$ $[e_1, e_4] =$ $[e_2, e_3] = e_5$ $[e_3, e_4] =$ $[e_2, e_5] = e_6$	$\mathcal{G}_{6,13}$

5. Six-dimensional nilpotent Lie algebras with center of dimension > 2 .

5.1. Let $G_k(V)$ be the set of k -dimensional linear subspaces of a linear space V . Then by Theorem 3.5, the orbits of $\text{Aut}(\mathcal{G})$ in $G_k(H^2(\mathcal{G}))$ determine isomorphism classes of Lie algebras $\tilde{\mathcal{G}}$ with $\dim \tilde{\mathcal{G}} = \dim \mathcal{G} + k$. Here $G_k(V)$ is a real-analytic compact manifold, and the action of $\text{Aut}(\mathcal{G})$ is real-analytic. We will consider the case

$$\dim \tilde{\mathcal{G}} = 6, \quad \dim \mathcal{G} \leq 4,$$

assuming that $\tilde{\mathcal{G}}$ does not have a direct abelian factor algebra.

If $\dim \mathcal{G} \leq 3$, then $S(\mathcal{G}) \subset \Lambda_2(\mathcal{G})$ implies that $\dim H^2(\mathcal{G}) \leq \dim \Lambda_2(\mathcal{G}) \leq 3$ with equality only for $\mathcal{G} = \mathbb{R}^3$. Thus we obtain the algebra $\tilde{\mathcal{G}} = \mathbb{R}^3(B_{12}, B_{23}, B_{13})$. When $\dim \mathcal{G} = 4$, we have $\mathcal{G} = \mathcal{G}_4, \mathbb{R} \times \mathcal{G}_3$, or \mathbb{R}^4 .

5.2. $\mathcal{G} = \mathcal{G}_4$: The product in \mathcal{G}_4 is $[e_1, e_2] = e_3, [e_1, e_3] = e_4$, and hence $S'(\mathcal{G}_4) = (B_{12}, B_{13}) \subset S(\mathcal{G}_4) = (B_{12}, B_{13}, B_{14}, B_{23})$, which gives the unique algebra $\tilde{\mathcal{G}} = \mathcal{G}_4(B_{14}, B_{23})$ of dimension 6.

5.3. $\mathcal{G} = \mathbb{R}^4$. In this case we have $H^2(\mathbb{R}^4) = \Lambda_2 \mathbb{R}^4$ of dimension 6 with basis $B_{ij}, 1 \leq i < j \leq 4$, and

$$\text{Aut}(\mathbb{R}^4) = \text{GL}(4).$$

$G_2(\Lambda_2 \mathbb{R}^4)$ is the union of 4 disjoint $\text{GL}(4)$ -invariant sets $\Omega_i, 1 \leq i \leq 4$. We first define the Ω_i , and then show that they actually are orbits of $\text{GL}(4)$. Let P be a two-dimensional subspace of $\Lambda_2 \mathbb{R}^4$.

$$\Omega_1 = \{P : \mathcal{J}_P \neq (0)\}$$

$$\Omega_2 = \{P : \mathcal{J}_P = (0) \quad \text{and} \quad P \text{ contains forms } B, B' \text{ with} \\ B \text{ of rank 2} \quad \text{and} \quad B' | \mathcal{J}_B \neq 0 \}$$

$$\Omega_3 = \{P : \mathcal{J}_P = (0) \text{ and } P = (B, B') \text{ where} \\ B \text{ is of rank 2 and } B' | \mathcal{J}_B = 0 \}$$

$$\Omega_4 = \{P : \text{any } B \in P \text{ is nondegenerate or trivial}\}.$$

5.3.1. Clearly $G_2(\Lambda_2 \mathbb{R}^4)$ is the union of the Ω_i . To show that Ω_1 is an orbit, let $P \in \Omega_1$. Then $\dim \mathcal{J}_P = 1$, and hence, setting $\mathbb{R}^3 = \mathbb{R}^4 / \mathcal{J}_P$, we obtain a plane $P' \in G_2(\Lambda_2 \mathbb{R}^3)$. The exterior product $(\Lambda_2 \mathbb{R}^3) \otimes (\mathbb{R}^3)^* = \Lambda^2(\mathbb{R}^3)^* \otimes (\mathbb{R}^3)^* \rightarrow \Lambda^3(\mathbb{R}^3)^* = \mathbb{R}$, defines a $GL(3)$ -invariant isomorphism $G_2(\Lambda_2 \mathbb{R}^3) = G_2(\mathbb{R}^3)$, and hence $GL(3)$ is acting transitively on $G_2(\Lambda_2 \mathbb{R}^3)$. Also $GL(4)$ is acting transitively on the set of lines through the origin in \mathbb{R}^4 , such as \mathcal{J}_P , and hence it follows that $GL(4)$ is acting transitively on Ω_1 . By the same reasoning, $SO(4)$ is acting transitively on Ω_1 , and one can show that $\Omega_1 = SO(4)/\mathbb{Z}_2 \times O(2)$.

5.3.2. For $P \in \Omega_2$, we will choose a basis for \mathbb{R}^4 such that there is a basis B, B' of P which has a standard matrix form in terms of the basis for \mathbb{R}^4 . It will follow that Ω_2 is an orbit of $GL(4)$. To find such a basis, let B be of rank 2, and $B' | \mathcal{J}_B \neq 0$. Choose $e_i \in \mathbb{R}^4$ such that $\mathcal{J}_B = (e_3, e_4)$ and $\text{Ker } B'(e_3, -) \cap \text{Ker } B'(e_4, -) = (e_1, e_2)$. Since $B' | \mathcal{J}_B$ is nonsingular, we have a basis for \mathbb{R}^4 , in terms of which $B = aB_{12}$ and $B' = bB_{12} + cB_{34}$, $ac \neq 0$. Hence P has standard form $P = (B_{12}, B_{34})$. It follows that the isotropy group of P has identity component $(GL(2) \times GL(2))^0$, and hence that $\dim \Omega_2 = 16 - 8 = 8 = \dim G_2(\Lambda_2 \mathbb{R}^4)$ so that Ω_2 is an open orbit. Because (B_{12}, B_{34}) is invariant under $A = \text{diag}(-1, 1, 1, 1)$, it follows that Ω_2 is connected.

5.3.3. When $P \in \Omega_3$, we have $P = (B, B')$ where B is of rank 2 and $B' | \mathcal{J}_B = 0$. We will find a suitable basis for \mathbb{R}^4 .

If $\mathcal{J}_{B'} + \mathcal{J}_B = \mathbb{R}^4$, we clearly have $B' = 0$. Hence, if $\dim \mathcal{J}_{B'} = 2$, we obtain $\mathcal{J}_P = \mathcal{J}_{B'} \cap \mathcal{J}_B \neq (0)$, contrary to the definition of Ω_3 . It follows that $\dim \mathcal{J}_{B'} = 0$, that is, B' is nondegenerate, and we can choose a basis for \mathbb{R}^4 such that $\mathcal{J}_B = (e_3, e_4)$ and $\text{Ker } B'(e_3, -) = (e_3, e_4, e_2)$, $B'(e_1, e_3) = 1$, $\text{Ker } B'(e_4, -) = (e_3, e_4, e_1)$, and $B'(e_2, e_4) = 1$.

Then $B = aB_{12}$, $B' = B_{13} + B_{24}$ and $P = (B_{12}, B_{13} + B_{24})$ and hence Ω_3 is a single orbit. One can show that the Lie algebra of the isotropy group of P (the isotropy algebra, see 5.4.3) is

$$\mathcal{G}_P = \left\{ \left(\begin{array}{c|c} A & 0 \\ \hline B & cI - A^t \end{array} \right) : A, B \in \mathfrak{gl}(2), c \in \mathbb{R} \right\},$$

and hence that $\dim \Omega_3 = 16 - 9 = 7$. Ω_3 has two components because the orientation of \mathbb{R}^4 defined by the chosen basis (e_1, e_2, e_3, e_4) depends only on P .

5.4.3. In order to show that Ω_4 is a single orbit, we will do as follows: First we will find a connected subset C of Ω_4 such that every $GL(4)$ -orbit in Ω_4 meets C . Next we will show that each point in C lies in an open $GL(4)$ -orbit. It then follows that C lies in a single orbit, which now must equal Ω_4 . To find the set C , let $P = (B, B') \in \Omega_4$, and choose a plane $\pi_1 \subset \mathbb{R}^4$ such that $B|_{\pi_1} \neq 0$ and $B'|_{\pi_1} \neq 0$. Then there are unique planes $\pi_2, \pi_3 \subset \mathbb{R}^4$ such that $B(\pi_1, \pi_2) = 0$ and $B'(\pi_1, \pi_3) = (0)$. There is a number c such that $B'|_{\pi_1} = cB|_{\pi_1}$. It follows that $(B' - cB)|(\pi_1 + (\pi_2 \cap \pi_3)) = 0$. Since $B' - cB$ is nondegenerate, $\dim(\pi_1 + (\pi_2 \cap \pi_3)) \leq 2$, and hence $\pi_2 \cap \pi_3 = (0)$. It follows that $\pi_i \cap \pi_j = (0)$ for $1 \leq i < j \leq 3$.

Lemma. $GL(4)$ is acting transitively on the set of triples (π_1, π_2, π_3) where π_i are planes in \mathbb{R}^4 such that $\pi_i \cap \pi_j = (0)$ for $i \neq j$.

Proof. Clearly, $GL(4)$ is acting transitively on the set of pairs (π_1, π_2) where $\pi_1 \cap \pi_2 = (0)$. Hence it suffices to show that $GL(2)^2 = GL(\pi_1) \times GL(\pi_2)$ is acting transitively on the set of all planes π_3 with $\pi_3 \cap \pi_1 = \pi_3 \cap \pi_2 = (0)$. Because $\pi_3 \cap \pi_2 = (0)$, there is a linear map $\varphi: \pi_1 \rightarrow \pi_2$ such that

$$\pi_3 = \{v + \varphi(v) : v \in \pi_1\},$$

and φ is an isomorphism because $\text{Ker } \varphi = \pi_1 \cap \pi_3 = (0)$.

For $(A_1, A_2) \in GL(2)^2 \subset GL(4)$, we have

$$(A_1, A_2)(\pi_3) = \{A_1 v + A_2 \varphi(v) : v \in \pi_1\} = \{v + A_2 \varphi A_1^{-1}(v) : v \in \pi_1\},$$

and since the action $(A_1, A_2)\varphi = A_2 \varphi A_1^{-1}$ on the set of linear isomorphisms $\varphi: \pi_1 \rightarrow \pi_2$ is transitive, the proof is complete.

It follows from the lemma that there is some $P' = (B_1, B_2)$ in the $GL(4)$ -orbit of P such that $B_1(\pi_1, \pi_2) = (0)$ and $B_2(\pi_1, \pi_3) = (0)$ where

$$\pi_1 = (e_3, e_4), \quad \pi_2 = (e_1, e_2), \quad \text{and} \quad \pi_3 = (e_1 + e_3, e_2 + e_4).$$

The only B_1, B_2 satisfying this condition are

$$\begin{aligned} B_1 &= aB_{12} + bB_{34}, \quad ab \neq 0, \quad \text{and} \\ B_2 &= cB_{12} + d(B_{12} + B_{23} - B_{14}), \quad d \neq 0, \end{aligned}$$

where B_2 is nondegenerate for $d \neq 0$. It follows that

$$P' = (B_{12} + b'B_{34}, c'B_{34} + B_{23} - B_{14}), \quad b' \neq 0.$$

Choose $x > 0$ and $\epsilon = \pm 1$ such that $x^2 b' = -\epsilon$ and set $\alpha = -xc'$. Then the matrix $\text{diag}(1, 1, x, -x)$ will transform P' to

$$P'' = (B_{12} + \epsilon B_{34}, \alpha B_{34} + B_{23} + B_{14}) = P(\alpha, \epsilon).$$

$$\begin{aligned} \det(s(B_{12} + \epsilon B_{34}) + t(\alpha B_{34} + B_{23} + B_{14})) &= (s(\epsilon s + \alpha t) + t^2)^2 = \\ &= ((t + \alpha s/2)^2 - (\alpha^2 - 4\epsilon)s^2/4)^2. \end{aligned}$$

This polynomial in s and t contains a linear factor if and only if $\alpha^2 \geq 4\epsilon$, and $P(\alpha, \epsilon)$ will then contain a degenerate form.

Hence there is a connected subset C of Ω_4 ,

$$C = \{P(\alpha, 1) : |\alpha| < 2\} = \{P(\alpha, \epsilon) : P(\alpha, \epsilon) \in \Omega_4\}$$

To complete the proof that Ω_4 is a single orbit, it suffices to show that each of the planes $P(\alpha, 1)$, $|\alpha| < 2$, lies on an open orbit in $G_2(\Lambda_2 \mathbb{R}^4)$.

For $B \in \Lambda_2 \mathbb{R}^4$ and $A \in \mathfrak{gl}(4)$, we set $B^A(v, w) = B(e^{tA}v, e^{tA}w)'_0 = B(Av, w) + B(v, Aw)$. Then the isotropy algebra of a plane $P \subset \Lambda_2 \mathbb{R}^4$ is

$$\mathcal{G}_P = \{A \in \mathfrak{gl}(4) : B^A \in P \text{ for all } B \in P\}.$$

Setting $P = (B_1, B_2)$, the conditions $B_1^A, B_2^A \in P$ are a system of linear equations in the entries of A , and the rank of this system equals $\dim \mathfrak{gl}(4) - \dim \mathcal{G}_P$, which is equal to $\dim \Omega(P)$. To write down those equations for the plane $P(\alpha, \epsilon)$, we note that, with $A = (a_{ij})$,

$$(B_{ij})^A = \sum_{k=1}^4 (a_{ik} B_{kj} - a_{jk} B_{ki}).$$

Setting $B_1 = B_{12} + \epsilon B_{34}$ and $B_2 = \alpha B_{34} + B_{23} + B_{14}$, we have

$$\begin{aligned} B_1^A &= (a_{23} - \epsilon a_{41})B_{13} + (-a_{14} + \epsilon a_{32})B_{24} \\ &\quad + (a_{11} + a_{22})B_{12} + \epsilon(a_{33} + a_{44})B_{34} \\ &\quad - (a_{23} + \epsilon a_{42})B_{23} + (a_{24} + \epsilon a_{31})B_{14}, \end{aligned}$$

and

$$\begin{aligned} B_2^A &= (-\alpha a_{41} + a_{21} + a_{43})B_{13} + (\alpha a_{32} + a_{34} + a_{12})B_{24} \\ &\quad + (-a_{31} + a_{42})B_{12} + (\alpha a_{33} + \alpha a_{44} - a_{24} + a_{13})B_{34} \\ &\quad + (-\alpha a_{42} + a_{22} + a_{33})B_{23} + (\alpha a_{31} + a_{11} + a_{44})B_{14}. \end{aligned}$$

The condition $B_1^A \in (B_1, B_2)$ is expressed by the 4 equations

$$(1) \quad a_{23} - \epsilon a_{41} = 0 \quad (2) \quad a_{32} - \epsilon a_{14} = 0$$

$$(3) \quad a_{24} + \epsilon a_{31} + a_{13} + \epsilon a_{42} = 0$$

$$(4) \quad a_{33} + a_{44} - a_{11} - a_{22} + \alpha \epsilon a_{13} + \alpha a_{42} = 0,$$

and the condition $B_2^A \in (B_1, B_2)$ by

$$(5) \quad a_{21} - \alpha a_{41} + a_{43} = 0 \quad (6) \quad a_{12} + \alpha a_{32} + a_{34} = 0$$

$$(7) \quad a_{11} - a_{22} + a_{44} - a_{33} + \alpha a_{42} + \alpha a_{31} = 0$$

$$(8) \quad a_{24} - \epsilon a_{31} + \alpha a_{22} - \alpha a_{44} - a_{13} + (\epsilon - \alpha^2) a_{42} = 0$$

The system S_1 formed by the equations numbered (1), (2), (5), and (6) involve only the 8 variables $a_{12}, a_{21}, a_{23}, a_{32}, a_{14}, a_{41}, a_{34},$ and a_{43} and this system is of rank 4.

The system S_2 formed by the equations numbered (3), (4), (7), and (8) involve only the 8 remaining variables $a_{13}, a_{31}, a_{24}, a_{42},$ and a_{ii} . The linear space generated by the coefficient couloumns of S_2 is generated by the coefficient couloumns of $a_{24}, a_{11}, a_{22},$ and $a_{13},$ and the coefficient matrix of those variables is

$$M = \begin{pmatrix} 1 & 0 & 0 & 1 \\ 0 & -1 & -1 & \epsilon \alpha \\ 0 & 1 & -1 & 0 \\ 1 & 0 & \alpha & -1 \end{pmatrix} \quad \text{with } \det M = \epsilon \alpha^2 - 4.$$

Hence S_2 has rank 4 if $\alpha^2 \neq 4\epsilon$, and has rank 3 if $\alpha^2 = 4\epsilon$, and the whole system (1) through (8) has rank 8 if $\alpha^2 \neq 4\epsilon$ and has rank 7 if $\alpha^2 = 4\epsilon$.

It follows that $\dim \Omega(P(\alpha, \epsilon)) = 8$ when $\alpha^2 \neq 4\epsilon$, and hence that each $P(\alpha, \epsilon)$ contained in C lies on an open orbit, completing the proof.

5.4. Theorem. $G_2(\Lambda_2 \mathbb{R}^4)$ is the union of four $GL(4)$ -orbits Ω_i , $1 \leq i \leq 4$, such that

$$\begin{aligned} (B_{12}, B_{23}) &\in \Omega_1, \quad \dim \Omega_1 = 5, \\ (B_{12}, B_{34}) &\in \Omega_2, \quad \dim \Omega_2 = 8, \\ (B_{12}, B_{13}+B_{24}) &\in \Omega_3, \quad \dim \Omega_3 = 7, \text{ and} \\ (B_{12}+B_{34}, B_{23}+B_{14}) &\in \Omega_4, \quad \dim \Omega_4 = 8. \end{aligned}$$

Remark. To determine the orbit Ω_i to which a given plane $P \subset \Lambda_2 \mathbb{R}^4$ belongs, one can proceed as follows. Let e_i , $1 \leq i \leq 4$ be the standard basis of \mathbb{R}^4 and define a symmetric bilinear form on $\Lambda_2 \mathbb{R}^4$ by $\langle B_1, B_2 \rangle = \frac{1}{4} \sum_{\sigma} \text{sgn}(\sigma) B_1(e_{\sigma(1)}, e_{\sigma(2)}) B_2(e_{\sigma(3)}, e_{\sigma(4)})$, the summation extending over all permutations of $\{1, 2, 3, 4\}$. In terms of the basis B_{ij} for $\Lambda_2 \mathbb{R}^4$, we have $\langle B_{\sigma(1)\sigma(2)}, B_{\sigma(3)\sigma(4)} \rangle = \text{sgn}(\sigma)$ and $\langle B_{ij}, B_{jk} \rangle = 0$, and hence $\langle \cdot, \cdot \rangle$ is a nondegenerate symmetric form on $\Lambda_2 \mathbb{R}^4$ of signature $(3, 3)$. Restricting this form to P , we obtain $\langle \cdot, \cdot \rangle_P$, and the orbit containing P is characterized as follows.

$$\begin{aligned} \langle \cdot, \cdot \rangle_P &= 0 \iff P \in \Omega_1, \\ \langle \cdot, \cdot \rangle_P &\text{ is of rank one } \iff P \in \Omega_3, \\ \langle \cdot, \cdot \rangle_P &\text{ is nonsingular, indefinite } \iff P \in \Omega_2, \\ \langle \cdot, \cdot \rangle_P &\text{ is nonsingular and definite } \iff P \in \Omega_4. \end{aligned}$$

The orbits Ω_3 and Ω_4 both have two components corresponding to those P with $\langle \cdot, \cdot \rangle_P$ positive or negative semidefinite.

5.5. $\mathcal{G} = \mathbb{R} \times \mathcal{G}_3$: $[e_1, e_2] = e_3$, e_4 is central,

$$S(\mathcal{G}) = (B_{13}, B_{23}, B_{14}, B_{24}, B_{12}), \quad S'(\mathcal{G}) = (B_{12}).$$

The automorphisms of \mathcal{G} have matrix form

$$A = \begin{pmatrix} a & b & 0 & 0 \\ c & d & 0 & 0 \\ r & s & \delta & \beta \\ t & u & 0 & \alpha \end{pmatrix}, \quad \delta = ad - bc.$$

The automorphism induced by A in $H^2(\mathcal{G})$ does not depend on r, s, t , and u . Hence, it suffices to take $A = \varphi\psi = \psi\varphi$ where

$$\varphi = \begin{pmatrix} a & b & 0 & 0 \\ c & d & 0 & 0 \\ 0 & 0 & \delta & 0 \\ 0 & 0 & 0 & \delta \end{pmatrix}, \quad \psi = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & \beta \\ 0 & 0 & 0 & \alpha \end{pmatrix},$$

and we have

$$(5.1) \quad \begin{aligned} B_{1j} \circ \varphi &= \delta(aB_{1j} + bB_{2j}), & B_{i3} \circ \psi &= B_{i3} + \beta B_{i4}, \\ B_{2j} \circ \varphi &= \delta(cB_{1j} + dB_{2j}), & B_{i4} \circ \psi &= \alpha B_{i4}, \end{aligned} \quad i = 1, 2, \quad j = 3, 4.$$

Theorem. There are 7 orbits of $\text{Aut}(\mathbb{R} \times \mathcal{G}_3)$ in $G_2(H^2(\mathbb{R} \times \mathcal{G}_3))$. We write them as $\mathcal{O}_0, \mathcal{O}_1, \mathcal{O}_3, \mathcal{Q}_1, \mathcal{Q}_3, \mathcal{Q}_4$, and \mathcal{Q}_4^c where the subscript is the dimension of the orbit, and

$$\begin{aligned} \{(B_{14}, B_{24})\} &= \mathcal{O}_0 \\ (B_{14}, B_{13}) &\in \mathcal{O}_1 \\ (B_{14}, B_{23}) &\in \mathcal{O}_3 \\ (B_{13}, B_{23}) &\in \mathcal{Q}_1 \\ (B_{13}, B_{23} + B_{14}) &\in \mathcal{Q}_3 \\ (B_{13}, B_{23} + B_{24}) &\in \mathcal{Q}_4 \\ (B_{13} + B_{24}, B_{23} - B_{14}) &\in \mathcal{Q}_4^c \end{aligned}$$

Proof. It follows from (5.1) that $P_4 = (B_{14}, B_{24})$ is $\text{Aut}(\mathcal{G})$ -invariant. Let X be the closed subspace of $G_2(H^2(\mathcal{G}))$ consisting of the planes P with $P \cap P_4 \neq 0$. It is not difficult to see that X is the disjoint union of the following three sets,

$$\mathcal{O}_0 = \{P_4\}$$

$$\mathcal{O}_1 = \{(sB_{14}+tB_{24}, sB_{13}+tB_{23}) : (s,t) \neq (0,0)\}$$

$$\mathcal{O}_3 = \{(sB_{14}+tB_{24}, u(tB_{14}-sB_{24})+s_1B_{13}+t_1B_{23}) : \\ (s,t) \neq (0,0), (s_1,t_1) \neq (0,0), (u, st_1-ts_1) \neq (0,0)\}$$

By directly computing the orbit through (B_{14}, B_{13}) and (B_{14}, B_{23}) , using formulas (5.1), we find that they are \mathcal{O}_1 and \mathcal{O}_3 . Clearly $\dim \mathcal{O}_1 = 1$, and $\dim \mathcal{O}_3 = \dim X = 3$.

Next we have to consider the planes P with $P \cap P_4 = (0)$. Let $\pi : H^2(\mathcal{G}) \rightarrow (B_{13}, B_{23})$ be the projection with kernel P_4 . Then $\pi(P) = (B_{13}, B_{23})$ and hence $P = (B_{13}+v_1, B_{23}+v_2)$ where $v_1, v_2 \in P_4$ are uniquely determined by P . Setting

$$\begin{aligned} v_1 &= a_{11}B_{14} + a_{21}B_{24}, \\ v_2 &= a_{12}B_{14} + a_{22}B_{24}, \end{aligned} \quad A(P) = \begin{pmatrix} a_{11} & a_{21} \\ a_{12} & a_{22} \end{pmatrix},$$

the matrix $A(P)$ is uniquely determined by P , and every 2 by 2 matrix A is of the form $A(P)$ for a unique P . Setting $A(P)\varphi = A(P \circ \varphi)$ and $A(P)\psi = A(P \circ \psi)$, a direct computation, using (5.1) shows that, for any A ,

$$A\varphi = \begin{pmatrix} a & b \\ c & d \end{pmatrix}^{-1} A \begin{pmatrix} a & b \\ c & d \end{pmatrix}, \quad A\psi = \alpha A + \beta I.$$

This defines an action of $\text{Aut}(\mathcal{G})$ in the affine space of 2 by 2 matrices, and it is not difficult to see that the orbits are

Q_1 : scalar matrices,

Q_3 : matrices with only one eigenvalue, but which are not scalar,

Q_4 : matrices with two real eigenvalues, and

Q_4^c : matrices with complex eigenvalues.

Here Q_4 and Q_4^c are open orbits. Also, $\dim Q_3 = 3$ because $Q_3 \cup Q_1$ is the variety in \mathbb{R}^4 defined by $(a_{11}-a_{22})^2 = 4a_{12}a_{21}$.

Choosing representatives for the orbits such as $\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$, $\begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$, $\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$, and $\begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$, we obtain representatives for the corresponding orbits in $G_2(H^2(\mathcal{G}))$,

$$(B_{13}, B_{23}) \in Q_1, (B_{13}, B_{23} + B_{14}) \in Q_3$$

$$(B_{13}, B_{23} + B_{24}) \in Q_4, (B_{13} + B_{24}, B_{23} - B_{14}) \in Q_4^c.$$

This completes the proof of the theorem. We note that \mathcal{O}_0 and Q_1 are degenerate orbits in the sense that $\mathcal{J}_{P_4} \cap \mathcal{J} = (e_3) \neq (0)$ and $\mathcal{J}_{B_{13}} \cap \mathcal{J}_{B_{23}} \cap \mathcal{J} = (e_4) \neq (0)$. Hence, there are 5 Lie algebras with center of dimension 2 obtained from the remaining 5 orbits.

5.6. Table. Six-dimensional real nilpotent Lie algebras $\tilde{\mathcal{G}}$ with center $\tilde{\mathcal{J}}$ of dimension ≥ 2 . $\mathcal{G} = \tilde{\mathcal{G}}/\tilde{\mathcal{J}}$.

\mathcal{G}	Defining orbit in $G_k(H^2(\mathcal{G}))$; $k = 2, 3$	Product in $\tilde{\mathcal{G}}$ (only non-zero brackets are given).	$\tilde{\mathcal{G}}$
\mathbb{R}^3	$k = 3$ $\{H^2(\mathcal{G})\} = \{\Lambda_2 \mathbb{R}^3\}$	$[e_1, e_2] = e_4$ $[e_2, e_3] = e_5$ $[e_1, e_3] = e_6$	$\mathcal{G}_{6,14}$
\mathbb{R}^4	$k = 2$ Ω_2	$[e_1, e_2] = e_5$ $[e_3, e_4] = e_6$	$\mathcal{G}_3 \times \mathcal{G}_3$
	Ω_3	$[e_1, e_2] = e_5$ $[e_1, e_3] = [e_2, e_4] = e_6$	$\mathcal{G}_{6,15}$
	Ω_4	$[e_1, e_2] = [e_3, e_4] = e_5$ $[e_2, e_3] = [e_1, e_4] = e_6$	$\mathcal{G}_{6,16}$
$\mathbb{R} \times \mathcal{G}_3$	$k = 2$ \mathcal{O}_1	$[e_1, e_2] = e_3$ $[e_1, e_3] = e_5$ $[e_1, e_4] = e_6$	$\mathcal{G}_{6,17}$
	\mathcal{O}_3	$[e_1, e_2] = e_3$ $[e_2, e_3] = e_5$ $[e_1, e_4] = e_6$	$\mathcal{G}_{6,18}$

	Q_3	$[e_1, e_2] = e_3 \quad [e_1, e_3] = e_5$ $[e_1, e_4] = [e_2, e_3] = e_6$	$\mathcal{G}_{6,19}$
	Q_4	$[e_1, e_2] = e_3 \quad [e_1, e_3] = e_5$ $[e_2, e_3] = [e_2, e_4] = e_6$	$\mathcal{G}_{6,20}$
	Q_4^c	$[e_1, e_2] = e_3 \quad [e_1, e_3] = [e_2, e_4] = e_5$ $[e_2, e_3] = -[e_1, e_4] = e_6$	$\mathcal{G}_{6,21}$
\mathcal{G}_4	$k=2$ $\{H^2(\mathcal{G})\} =$ $\{(B_{14}, B_{23})\}$	$[e_1, e_2] = e_3 \quad [e_1, e_3] = e_4$ $[e_1, e_4] = e_5 \quad [e_2, e_3] = e_6$	$\mathcal{G}_{6,22}$

5.7. Clearly the real nilpotent Lie algebras of dimension six containing direct factors are, within isomorphisms,

$$\mathcal{G}_1^6 ; \mathcal{G}_3 \times \mathcal{G}_1^3 ; \mathcal{G}_4 \times \mathcal{G}_1^2 ; \mathcal{G}_{5,i} \times \mathcal{G}_1, 1 \leq i \leq 6 ; \mathcal{G}_3 \times \mathcal{G}_3 .$$

Theorem. Every six-dimensional real nilpotent Lie algebra with no nontrivial direct factor is isomorphic to one of the following algebras

$$\mathcal{G}_{6,1}, \mathcal{G}_{6,2}, \dots, \mathcal{G}_{6,22} .$$

These algebras are pairwise nonisomorphic.

Reference

J. Dixmier, Sur les représentations unitaires des groupes de Lie nilpotents, III, Canadian Journal of mathematics, 10 (1958) 321-348.